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# Analysis on an Improved Global Convergence for a Spectral Conjugate Gradient Method

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#### ABSTRACT

In this paper, we establish the theory of global convergence for a spectral conjugate gradient algorithm recently developed by Z. Wan etc. An assumption, that the inequalities  $0 < g_k^T g_{k-1} \le 2||g_k||^2$  are satisfied for any k, is first investigated by numerical experiments. It is shown that such assumption holds only for k large enough in solving some benchmark problems, not for all ones. Another contribution of this paper is to obtain the same convergence result under some weaker assumptions.

Keywords: unconstrained optimization, conjugate gradient, global convergence

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## 1 Introduction

Consider the following unconstrained optimization problem:

$$\min f(x), \quad x \in \mathbb{R}^n, \tag{1.1}$$

where  $f: \mathbb{R}^n \to \mathbb{R}$  is continuously differentiable such that its gradient is available. Let g(x) denote the gradient of f at x.

Due to the features of low memory requirement and simple computation, the conjugate gradient method is popular to be employed for solving problem (1.1). By this method, starting from an initial point  $x_0 \in \mathbb{R}^n$ , a sequence of solutions  $x_k$ ,  $k \ge 1$ , is generated by

$$x_{k+1} = x_k + \alpha_k d_k,$$

where  $\alpha_k$  is a stepsize obtained by some line search rule and  $d_k$  is a search direction given by

$$d_k = \begin{cases} -g_k, & \text{if } k = 0, \\ -g_k + \beta_k d_{k-1}, & \text{if } k > 0. \end{cases}$$
 (1.2)

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In (1.2),  $\beta_k$  is a fundamental algorithmic parameter. With different value of  $\beta_k$ , the corresponding algorithm has distinct numerical behavior (see, for example, [5], [8], [10], [11], [12], [16], [22] and the references therein). One of the most popular choices is the formula given by the Polak-Ribière-Polyak conjugate gradient method, it reads

$$\beta_k^{PRP} = \frac{g_k^T(g_k - g_{k-1})}{\|g_{k-1}\|^2}.$$
 (1.3)

Very recently, in [15], a new spectral PRP conjugate gradient algorithm is developed. The search direction  $d_k$  is determined by

$$d_k = \begin{cases} -g_k, & \text{if } k = 0, \\ -\theta_k g_k + \beta_k^{PRP} d_{k-1}, & \text{if } k > 0, \end{cases}$$
 (1.4)

where

$$\theta_k = \frac{d_{k-1}^T y_{k-1}}{\|g_{k-1}\|^2} - \frac{d_{k-1}^T g_k g_k^T g_{k-1}}{\|g_k\|^2 \|g_{k-1}\|^2}.$$
(1.5)

The stepsize in the algorithm is obtained by the following modified Wolf-type line search rule:

$$\begin{cases} f(x_k) - f(x_k + \alpha_k d_k) \ge \rho \alpha_k^2 ||d_k||^2, \\ g(x_k + \alpha_k d_k)^T d_k \ge -2\sigma \alpha_k ||d_k||^2. \end{cases}$$
 (1.6)

Thus, the framework of the algorithm is described as follows.

## Algorithm 1. (Modified Spectral PRP Conjugate Gradient Algorithm)

Step 0 Given constants  $0 < \rho < \sigma < 1, \epsilon > 0$ . Choose an initial point  $x_0 \in \mathbb{R}^n$ . Set k := 0.

Step 1 If  $||g_k|| \le \epsilon$ , then the algorithm stops. Otherwise, compute  $d_k$  by (1.4) and (1.5), and go to Step 2.

Step 2 Determine a steplength  $\alpha_k > 0$  such that (1.6) is satisfied.

Step 3 Set  $x_{k+1} := x_k + \alpha_k d_k$ , and k := k + 1. Return to Step 1.

In [15], it has been demonstrated by numerical experiment that Algorithm 1 is powerful to solve the benchmark test problems from [9]. However, in [15], the establishment of global convergence needs the following assumption

$$0 < g_k^T g_{k-1} \le 2g_k^T g_k. (1.7)$$

To observe whether the inequalities (1.7) hold or not, we implement Algorithm 1 to solve some test problems from [9], with choices of  $\rho = 0.5$ ,  $\sigma = 0.75$  and  $\epsilon = 10^{-7}$ . In Table 1, the results are reported, which indicate that (1.7) must not hold in some cases.

Table 1: Results of testing assumption

Function	$x_0$	total times	$0 < g_k^T g_{k-1} \le 2g_k^T g_k$
Rosenbrock	(-1.2,1)	90	None
Helical valley	(-1,0,0)	103	None
Box three-dimensional	(0,10,20)	6867	$k \ge 6866$
Biggs EXP6	(1,2,1,1,1,1)	57560	$k \ge 57552$

The numerical experiments show that the probability that (1.7) is satisfied reduces in the case that the number of iterations is small, but for a large number of iterations, it is often that the inequalities (1.7) hold.

Motivated by the above observation, we are going to establish the global convergence of Algorithm 1 without Assumption (1.7), but the same convergence result as that in [15] is to be obtained.

This paper is organized as follows. In the next section, the main results will be presented. Section 3 will be devoted to prove the main results. Some final remarks are given in the last section.

#### 2 Main results

Assumption 1. The level set  $\Omega = \{x \in \mathbb{R}^n \mid f(x) \leq f(x_0)\}$  is bounded.

Assumption 2. In some neighborhood N of  $\Omega$ , f is continuously differentiable and its gradient is Lipschitz continuous, namely, there exists a constant L > 0 such that

$$||g(x) - g(y)|| \le L||x - y||, \quad \forall x, y \in N.$$
 (2.1)

**Lemma 2.1.** Suppose that  $d_k$  is given by (1.3)-(1.5). Then, the following result

$$g_k^T d_k = -\|g_k\|^2 (2.2)$$

holds for any  $k \geq 0$ .

Lemma 2.1 shows that the direction  $d_k$  in Algorithm 1 is always sufficiently descent at each iteration.

**Lemma 2.2.** With Assumption 2, there exists  $\alpha_k > 0$  satisfying (1.6).

In the following lemma, it is stated that the Zoutendijk condition holds, which is useful to prove the global convergence of conjugate gradient method (see [24] and [18]).

Lemma 2.3. Under Assumptions 1 and 2, it holds that

$$\sum_{k=0}^{\infty} \frac{\|g_k\|^4}{\|d_k\|^2} < \infty.$$

The following property of the algorithm plays an important role in the proof of the main theorem.

**Lemma 2.4.** Let  $\{\alpha_k\}$  and  $\{d_k\}$  be the step size and the search direction sequences generated by Algorithm 1, respectively. Then,

$$\lim_{k \to \infty} \alpha_k^2 ||d_k||^2 = 0.$$

With Lemmas 2.1, 2.2, 2.3 and 2.4, we can prove the global convergence.

**Theorem 2.5.** Let  $\{g_k\}$  be the gradient sequence generated by Algorithm 1. Under Assumptions 1 and 2, the following result

$$\lim_{k \to \infty} \inf \|g_k\| = 0. \tag{2.3}$$

holds.

## 3 Proof of main results

In this section, we present the proofs for the main results in this paper.

Since Lemmas 2.1, 2.2 and 2.3 are directly from the corresponding conclusions in [15] under the same conditions, we here needs to prove Lemma 2.4 and Theorem 2.5.

### The proof of Lemma 2.4:

From the line search strategy (1.6), we know

$$f(x_k) - f(x_{k+1}) \ge \rho \alpha_k^2 ||d_k||^2$$
.

Thus, it is obtained that

$$\sum_{k=1}^{n} (f(x_k) - f(x_{k+1})) \ge \rho \sum_{k=1}^{n} \alpha_k^2 ||d_k||^2.$$

Since f is bounded in the level set  $\Omega$ , there exists a positive constant scalar M such that

$$2M \ge f(x_1) - f(x_{n+1}) \ge \rho \sum_{k=1}^{n} \alpha_k^2 ||d_k||^2.$$

It follows that the series

$$\sum_{k=1}^{\infty} \alpha_k^2 \|d_k\|^2$$

is convergent. Thus,

$$\lim_{k \to \infty} \alpha_k^2 ||d_k||^2 = 0. \tag{3.1}$$

The desired result is proved.

## The proof of Theorem 1:

If the result (2.3) does not hold, then there exists a positive  $\epsilon > 0$  such that for all k,  $||g_k|| \ge \epsilon$ . From (1.4), it follows that

$$\begin{aligned} \|d_k\|^2 &= d_k^T d_k \\ &= (-\theta_k g_k^T + \beta_k^{PRP} d_{k-1}^T)(-\theta_k g_k + \beta_k^{PRP} d_{k-1}) \\ &= \theta_k^2 \|g_k\|^2 - 2\theta_k \beta_k^{PRP} d_{k-1}^T g_k + (\beta_k^{PRP})^2 \|d_{k-1}\|^2 \\ &= \theta_k^2 \|g_k\|^2 - 2\theta_k d_k^T g_k - 2\theta_k^2 \|g_k\|^2 + (\beta_k^{PRP})^2 \|d_{k-1}\|^2 \\ &= (\beta_k^{PRP})^2 \|d_{k-1}\|^2 - 2\theta_k d_k^T g_k - \theta_k^2 \|g_k\|^2. \end{aligned}$$

Dividing by  $||g_k||^4$  on the both sides of this equality, we obtain

$$\begin{split} \frac{\|d_k\|^2}{\|g_k\|^4} &= \frac{(\beta_k^{PRP})^2 \|d_{k-1}\|^2 - 2\theta_k d_k^T g_k - \theta_k^2 \|g_k\|^2}{\|g_k\|^4} \\ &= \frac{(g_k^T (g_k - g_{k-1}))^2}{\|g_{k-1}\|^4} \frac{\|d_{k-1}\|^2}{\|g_k\|^4} - \frac{(\theta_k - 1)^2}{\|g_k\|^2} + \frac{1}{\|g_k\|^2} \\ &= \frac{(g_k^T (g_k - g_{k-1}))^2}{\|g_k\|^4} \frac{\|d_{k-1}\|^2}{\|g_{k-1}\|^4} - \frac{(\theta_k - 1)^2}{\|g_k\|^2} + \frac{1}{\|g_k\|^2} \\ &\leq \frac{\|g_k - g_{k-1}\|^2}{\|g_k\|^2} \frac{\|d_{k-1}\|^2}{\|g_{k-1}\|^4} + \frac{1}{\|g_k\|^2} \\ &\leq \frac{L^2 \alpha_{k-1}^2 \|d_{k-1}\|^2}{\epsilon^2} \frac{\|d_{k-1}\|^2}{\|g_{k-1}\|^4} + \frac{1}{\|g_k\|^2}. \end{split}$$

From Lemma 2.4, it is clear that there exists an integer number  $k_0 \ge 0$  such that for  $k \ge k_0$ , we have

 $0 \le \alpha_{k-1}^2 ||d_{k-1}||^2 < \frac{\epsilon^2}{L^2}.$ 

Thus,

$$\begin{aligned} \frac{\|d_k\|^2}{\|g_k\|^4} &< \frac{\|d_{k-1}\|^2}{\|g_{k-1}\|^4} + \frac{1}{\|g_k\|^2} \\ &\leq \ldots \leq \frac{\|d_{k_0}\|^2}{\|g_{k_0}\|^4} + \sum_{i=k_0+1}^k \frac{1}{\|g_i\|^2} \\ &\leq \frac{C_0}{\epsilon^2} + \frac{k - k_0}{\epsilon^2} \\ &= \frac{C_0 + (k - k_0)}{\epsilon^2}, \end{aligned}$$

where

$$C_0 = \epsilon^2 \frac{\|d_{k_0}\|^2}{\|g_{k_0}\|^4} > 0$$

is a constant. Therefore, it is obtained that

$$\sum_{k \ge 1} \frac{\|g_k\|^4}{\|d_k\|^2} \ge \sum_{k > k_0} \frac{\|g_k\|^4}{\|d_k\|^2} > \epsilon^2 \sum_{k > k_0} \frac{1}{C_0 + (k - k_0)} = \infty,$$

which contradicts the result of Lemma 2.4. This shows that the desired conclusion holds.

## 4 Final Remarks

In this paper, we have established the theory of global convergence for a class of spectral conjugate gradient methods. Different from the existing results available in the literature, we have obtained the same conclusion under more weaker assumption conditions.

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